



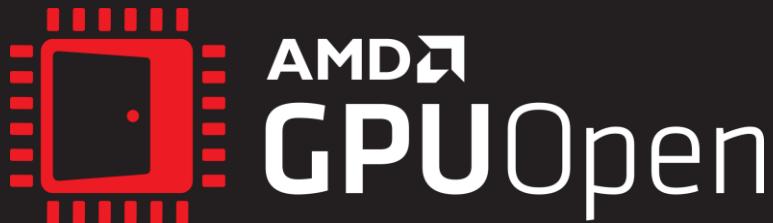
RADEON

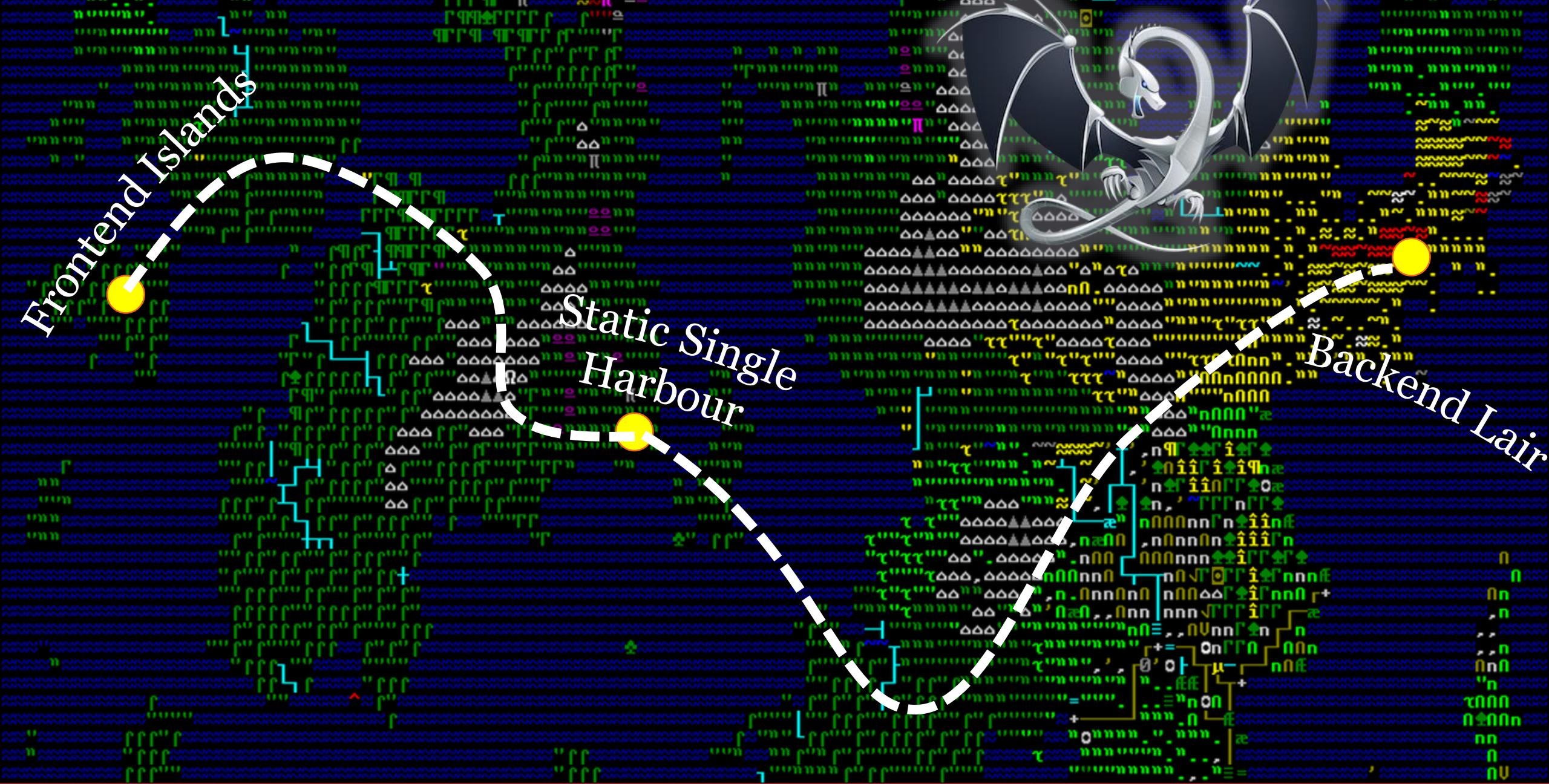


AMD

# A TRIP DOWN THE GPU COMPILER PIPELINE

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# QUICK!: HOW MANY FLOAT MULTIPLIES ARE IN THIS SHADER?

```
Buffer<float4> inputBuffer;
RWBuffer<float> outputBuffer;

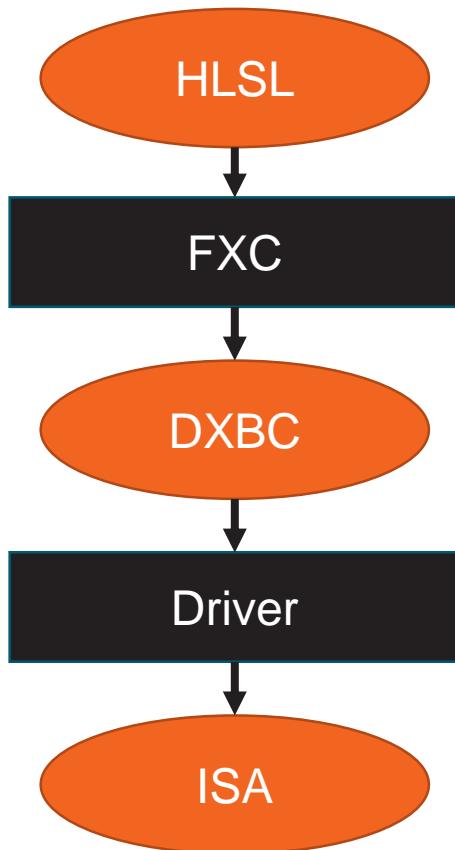
[numthreads(8,4,1)]
void CSMain(uint3 did : SV_DispatchThreadId)
{
    outputBuffer[did.x] = inputBuffer[did.x][did.y];
}
```

# QUICK! HOW MANY FLOAT MULTIPLIES ARE IN THIS SHADER?

Answer: 4

```
buffer_load_format_xyzw  v[0:3], v8, s[4:7], 0 idxen
tbuffer_load_format_xyzw  v[4:7], v4, s[12:15], 0 idxen
format:[BUF_FMT_32_32_32_32_FLOAT]
s_waitcnt    vmcnt(0)
v_mul_f32      v0, v0, v4
v_mac_f32     v0, v1, v5
v_mac_f32     v0, v2, v6
v_mac_f32     v0, v3, v7
v_mov_b32     v1, v0
v_mov_b32     v2, v0
v_mov_b32     v3, v0
buffer_store_format_xyzw  v[0:3], v8, s[8:11], 0 idxen
```

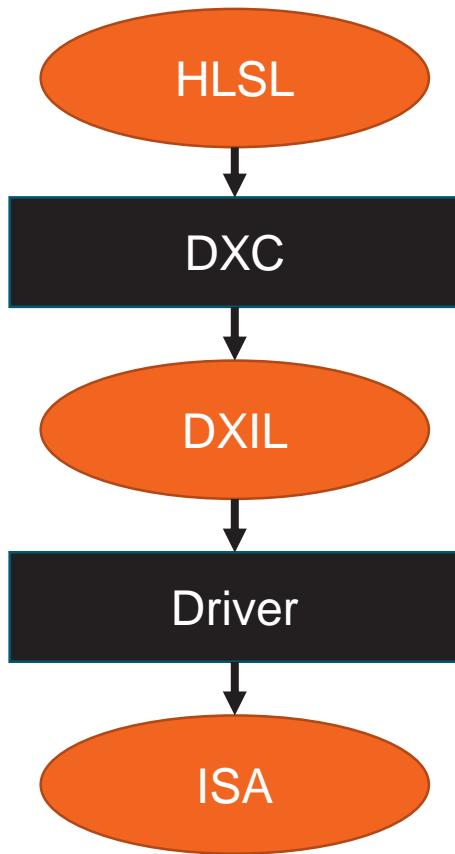
# COMPILER PIPELINE: DX11



```
cs_5_0
dcl_globalFlags refactoringAllowed
dcl_immediateConstantBuffer { { 1.000000, 0, 0, 0},
                               { 0, 1.000000, 0, 0},
                               { 0, 0, 1.000000, 0},
                               { 0, 0, 0, 1.000000} }

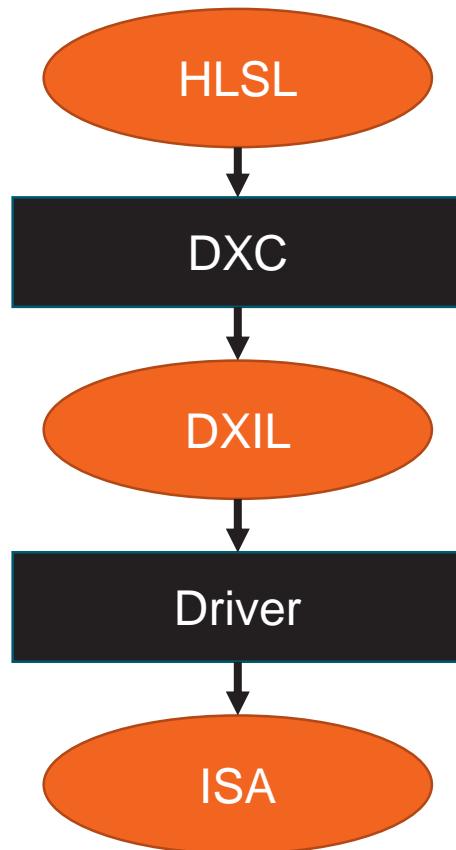
...
ld_indexable(buffer)(float,float,float,float) r0.xyzw, vThreadID.xxxx,
t0.xyzw
mov r1.x, vThreadID.y
dp4 r0.x, r0.xyzw, icb[r1.x + 0].xyzw
store_uav_typed u0.xyzw, vThreadID.xxxx, r0.xxxx
ret
```

# COMPILER PIPELINE: DX12



```
...
%6 = call ... @dx.op.bufferLoad.f32(i32 68, %dx.types.Handle %3, i32 %4, i32 undef)
%7 = extractvalue %dx.types.ResRet.f32 %6, 0
%8 = extractvalue %dx.types.ResRet.f32 %6, 1
%9 = extractvalue %dx.types.ResRet.f32 %6, 2
%10 = extractvalue %dx.types.ResRet.f32 %6, 3
%11 = getelementptr inbounds [4 x float], [4 x float]* %1, i32 0, i32 0
store float %7, float* %11, align 4
%12 = getelementptr inbounds [4 x float], [4 x float]* %1, i32 0, i32 1
store float %8, float* %12, align 4
%13 = getelementptr inbounds [4 x float], [4 x float]* %1, i32 0, i32 2
store float %9, float* %13, align 4
%14 = getelementptr inbounds [4 x float], [4 x float]* %1, i32 0, i32 3
store float %10, float* %14, align 4
%15 = getelementptr inbounds [4 x float], [4 x float]* %1, i32 0, i32 %5
%16 = load float, float* %15, align 4
call void @dx.op.bufferStore.f32(i32 69, %dx.types.Handle %2, i32 %4, i32 undef,
                                float %16, float %16, float %16, float %16, i8 15)
...
```

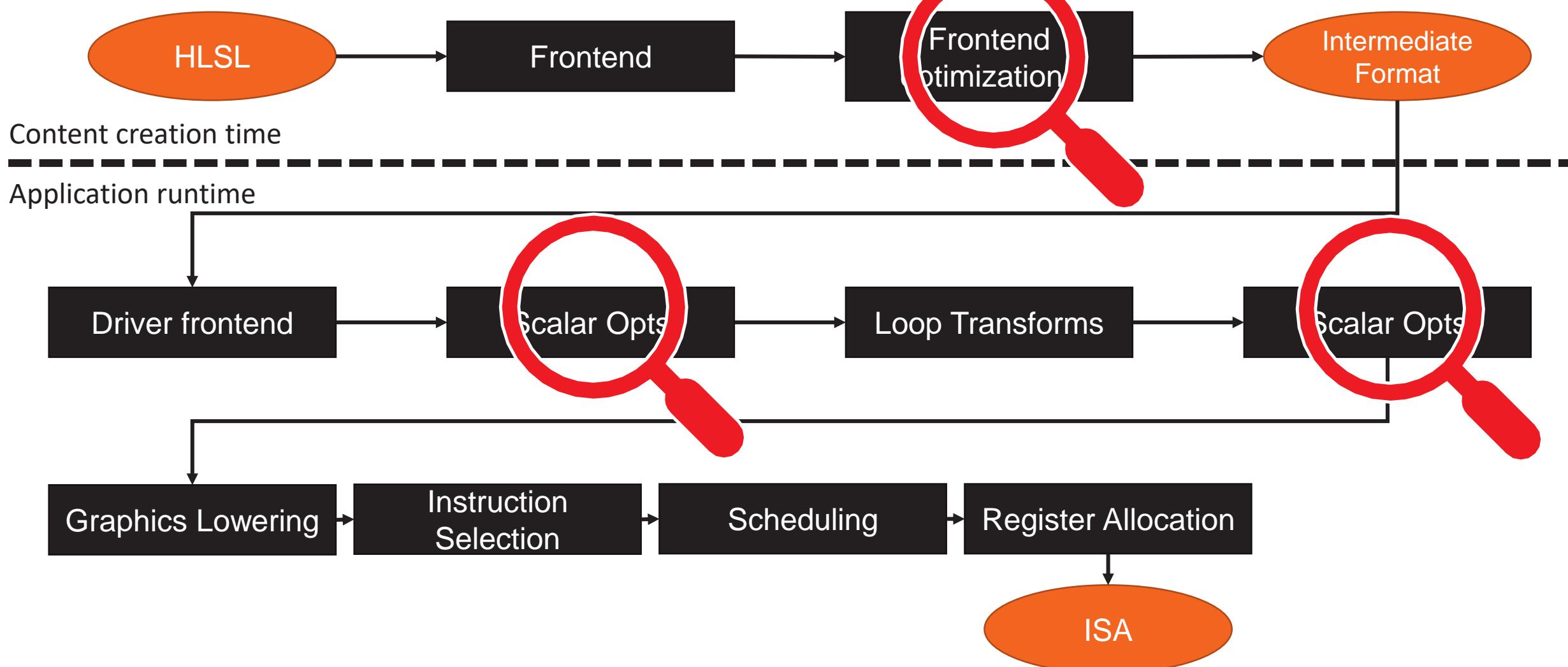
# COMPILER PIPELINE: DX12



```
...
v_cmp_eq_i32    s[4:5], v0, 0
v_cmp_eq_i32    s[6:7], v0, 1
v_cmp_eq_i32    vcc, 2, v0
s_waitcnt      lgkmcnt(0)
buffer_load_format_xyzw  v[0:3], v4, s[8:11], 0 idxen
s_waitcnt      vmcnt(0)
v_cndmask_b32   v2, v3, v2, vcc
v_cndmask_b32   v1, v2, v1, s[6:7]
v_cndmask_b32   v0, v1, v0, s[4:5]
v_mov_b32       v1, v0
v_mov_b32       v2, v0
v_mov_b32       v3, v0
buffer_store_format_xyzw  v[0:3], v4, s[0:3], 0 idxen glc
...
```



# COMPILER PIPELINE



# WHY IR?

- Unambiguous parsing
- Simpler type system

```
switch(commands[did.x]) {  
    case 0: result = i.x + i.y; break;  
    case 1: result = i.x - i.y; break;  
    case 2: result = i.x * i.y; break;  
    case 3: result = i.x / i.y; break;  
    default: break;  
}
```

```
; <label>:10  
%11 = fadd fast float %6, %7  
br label %18  
  
; <label>:  
%13 = fsub fast float %6, %7  
br label %18  
  
; <label>:  
%15 = fmul fast float %6, %7  
br label %18  
  
; <label>:  
%17 = fdiv fast float %6, %7  
br label %18
```

# TRANSLATING TO IR

- Vulkan®, Direct3D®11 and Direct3D®12 all go through an intermediate representation (SPIR-V, DXBC, DXIL)
- There is at least one more intermediate representation in the compiler
- This is (generally) a lossy conversion!
- For instance:
  - Types can change (as we saw, buffer types are all the same)
  - Things can disappear
  - Expressions can change

# LEGALIZATION

- Makes code “legal”
- Sometimes the high-level language is more expressive than the IR/backend
- Code needs to get “legalized” to be valid IR level code
- Simple example:
  - Imagine division is forbidden at the IR level.
  - Solution: Replace all divisions with multiply by reciprocal

# LEGALIZATION

```
Buffer<float4> inputBuffer0;
RWBuffer<float> outputBuffer;

float LoadAndProcess(Buffer<float4> b, int i)
{
    return dot(b[i], b[i]);
}

[numthreads(64,1,1)]
void CSMain(uint3 did : SV_DispatchThreadId)
{
    outputBuffer[did.x] = LoadAndProcess(inputBuffer0, did.x);
}
```

# LEGALIZATION

- It is illegal to pass a buffer into a function
- The IR **can** express it, but validation will fail

```
OpStore %param_var_i %34
%35 = OpFunctionCall %float %LoadAndProcess %param_var_b %param_var_i
%37 = OpAccessChain %_ptr_Function_uint %did %int_0
%38 = OpLoad %uint %37
%39 = OpLoad %type_buffer_image_0 %outputBuffer
      OpImageWrite %39 %38 %35 None

%LoadAndProcess = OpFunction %float None %41
%b = OpFunctionParameter %_ptr_Function_type_buffer_image
%i = OpFunctionParameter %_ptr_Function_int
```

# LEGALIZATION

- Legalization force-inlines the code
- Function call is removed; no parameter passing required, everyone is happy!

```
%21 = OpBitcast %int %20
%22 = OpBitcast %uint %21
%23 = OpImageFetch %v4float %19 %22 None
%24 = OpImageFetch %v4float %19 %22 None
%25 = OpDot %float %23 %24
%26 = OpLoad %type_buffer_image_0 %outputBuffer
          OpImageWrite %26 %20 %25 None
```

# BUFFER TYPES CAN CHANGE

- High-level language

```
Buffer<float> inputBuffer0 : register(t0);
RWBuffer<float> outputBuffer : register(u0);
```

```
[numthreads(64,1,1)]
void CSMain(uint3 did : SV_DispatchThreadId)
{
    outputBuffer[did.x] = inputBuffer0[did.x];
}
```

# BUFFER TYPES CAN CHANGE

- IR level

; inputBuffer0	texture	f32	buf	T0	t0	1
; outputBuffer	UAV	f32	buf	U0	u0	1

- DXASM

```
dcl_resource_buffer (float,float,float,float) T0[0:0], space=0
dcl_uav_typed_buffer (float,float,float,float) U0[0:0], space=0
```

- DXIL

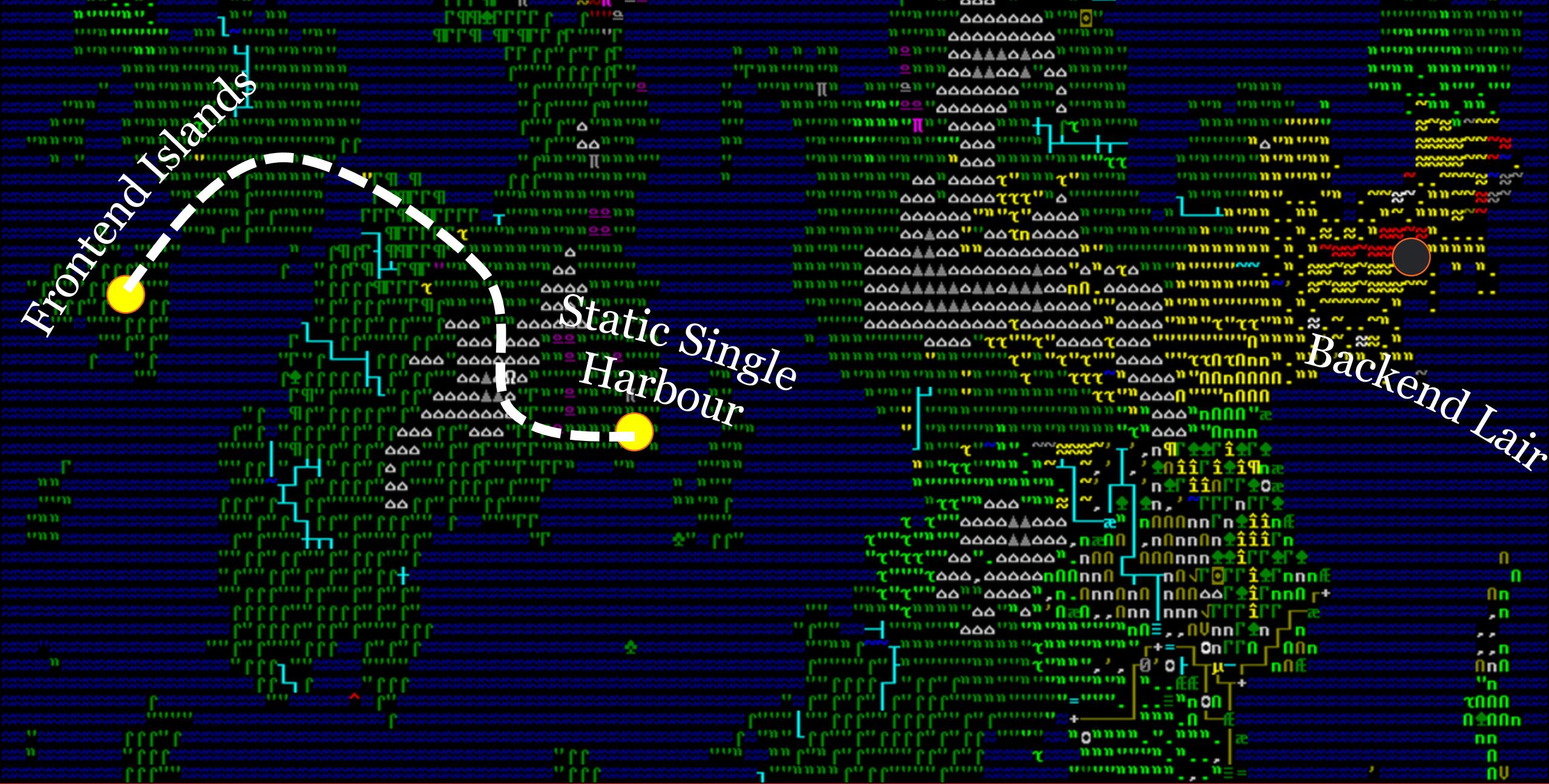
```
%"class.Buffer<float>" = type { float }
%"class.RwBuffer<float>" = type { float }
...
call void @dx.op.bufferStore.f32(i32 69, %dx.types.Handle %1, i32 %3, i32 undef,
    float %5, float %5, float %5, float %5, i8 15)
```

# BUFFER TYPES CAN CHANGE

- API flexibility sometimes requires compiler sacrifices
- Generated ISA

```
v_mov_b32      v3, v2
v_mov_b32      v4, v2
v_mov_b32      v5, v2
buffer_store_format_xyzw  v[2:5], v1, s[0:3], 0 idxen glc // 00000000004C: E01C6000 80000201
```

- 4 Registers get initialized and passed, even though you and I know this is not needed



# STATIC SINGLE ASSIGNMENT FORM (SSA)

- An important concept in compiler theory you need to know about
- Modern compilers use SSA
- Every variable gets assigned exactly once

```
x = 23;  
y = 37;  
x = x * y;  
...  
z = x;
```

```
x_0 = 23;  
y_0 = 37;  
x_1 = x_0 * y_0;  
...  
z_0 = x_1;
```

# SSA – BRANCHES & LOOPS

- SSA obviously doesn't work for branches and loops without this one weird trick
- Phi-nodes to the rescue

```
x = 23;  
if (y) {  
    x = 42;  
}  
z = x;
```

```
x_0 = 23;  
L1: if (y_0) {  
    x_1 = 42;  
}  
z = Φ(L1, x_0, x_1);
```

# SSA – PHI NODES

- Compiler needs to resolve Phi nodes
- This is where things get tricky, more so the more ways variables enter the Phi node
  - Loops with multiple exits
  - Switch statements
  - Complex control flow

# SSA – PHI NODES

- How many inputs does the Phi node have after this switch?

```
float result = 0;
float2 i = inputs[did.x];

switch (commands[did.x]) {
    case 0: result = i.x + i.y; break;
    case 1: result = i.x - i.y; break;
    case 2: result = i.x * i.y; break;
    case 3: result = i.x / i.y; break;
    default: break;
}

return result;
```

# SSA – PHI NODES

- Correct – 5!
- 4 case labels and the value before the switch in case you hit the default

```
%27 = phi float [ %12, %9 ], [ %16, %13 ], [ %20, %17 ], [ %24, %21 ], [ 0.000000e+00, %25 ]
```

# SCALAR OPTIMIZATIONS

- Dead-code elimination
- Constant folding
- Common sub-expression elimination
- Global value numbering
- Strength reduction

# CONSTANT FOLDING

- Trivial with SSA

```
#define BLOCK_WIDTH (6)
#define BLOCK_HEIGHT (6)

[numthreads(8,4,1)]
void CSMain(uint3 did : SV_DispatchThreadId)
{
    uint2 blockSize = uint2(BLOCK_WIDTH, BLOCK_HEIGHT);
    uint2 shifted = did.xy + blockSize / 2;           ← Oh no, a division!
    float4 color = input[shifted];
    output[did.xy] = color;
}
```

# CONSTANT FOLDING

```
%uint_6 = OpConstant %uint 6
         %9 = OpConstantComposite %v2uint %uint_6 %uint_6
%uint_2 = OpConstant %uint 2
         %11 = OpConstantComposite %v2uint %uint_2 %uint_2

%39 = OpLoad %v3uint %did
%40 = OpVectorShuffle %v2uint %39 %39 0 1

%42 = OpUDiv %v2uint %9 %11
%43 = OpIAdd %v2uint %40 %42
```



Direct frontend translation

# CONSTANT FOLDING

```
%uint_3 = OpConstant %uint 3
%12 = OpConstantComposite %v2uint %uint_3 %uint_3
```

```
%39 = OpLoad %v3uint %did
%40 = OpVectorShuffle %v2uint %39 %39 0 1
```

```
%43 = OpIAdd %v2uint %40 %12
```

# COMMON SUB-EXPRESSION ELIMINATION (CSE)

```
float a = (inputBuffer[did.x].x + inputBuffer[did.x].y) *
           inputBuffer[did.x].z;
float b = (inputBuffer[did.x].x + inputBuffer[did.x].y) *
           inputBuffer[did.x].w;
outputBuffer[did.x] = float2(a, b);
```

# COMMON SUB-EXPRESSION ELIMINATION (CSE)

```
...
%21 = OpImageFetch %v4float %20 %19 None
%22 = OpCompositeExtract %float %21 0
%23 = OpImageFetch %v4float %20 %19 None
%24 = OpCompositeExtract %float %23 1
%25 = OpFAdd %float %22 %24
%26 = OpImageFetch %v4float %20 %19 None
%27 = OpCompositeExtract %float %26 2
%28 = OpFMul %float %25 %27
%29 = OpImageFetch %v4float %20 %19 None
%30 = OpCompositeExtract %float %29 0
%31 = OpImageFetch %v4float %20 %19 None
%32 = OpCompositeExtract %float %31 1
%33 = OpFAdd %float %30 %32
%34 = OpImageFetch %v4float %20 %19 None
%35 = OpCompositeExtract %float %34 3
%36 = OpFMul %float %33 %35
%37 = OpCompositeConstruct %v2float %28 %36
...
...
```

# COMMON SUB-EXPRESSION ELIMINATION (CSE)

```
...
%21 = OpImageFetch %v4float %20 %19 None
%22 = OpCompositeExtract %float %21 0

%24 = OpCompositeExtract %float %21 1
%25 = OpFAdd %float %22 %24

%27 = OpCompositeExtract %float %21 2
%28 = OpFMul %float %25 %27

%30 = OpCompositeExtract %float %21 0

%32 = OpCompositeExtract %float %21 1
%33 = OpFAdd %float %30 %32

%35 = OpCompositeExtract %float %21 3
%36 = OpFMul %float %33 %35
%37 = OpCompositeConstruct %v2float %28 %36
...
```

# COMMON SUB-EXPRESSION ELIMINATION (CSE)

```
...
%21 = OpImageFetch %v4float %20 %19 None
%22 = OpCompositeExtract %float %21 0

%24 = OpCompositeExtract %float %21 1
%25 = OpFAdd %float %22 %24

%27 = OpCompositeExtract %float %21 2
%28 = OpFMul %float %25 %27

%33 = OpFAdd %float %22 %24

%35 = OpCompositeExtract %float %21 3
%36 = OpFMul %float %33 %35
%37 = OpCompositeConstruct %v2float %28 %36
...
```

# COMMON SUB-EXPRESSION ELIMINATION (CSE)

```
...
%21 = OpImageFetch %v4float %20 %19 None
%22 = OpCompositeExtract %float %21 0

%24 = OpCompositeExtract %float %21 1
%25 = OpFAdd %float %22 %24

%27 = OpCompositeExtract %float %21 2
%28 = OpFMul %float %25 %27

%35 = OpCompositeExtract %float %21 3
%36 = OpFMul %float %23 %35
%37 = OpCompositeConstruct %v2float %28 %36
...
```

# COMMON SUB-EXPRESSION ELIMINATION (CSE)

```
buffer_load_format_xyzw  v[0:3], v4, s[4:7], 0 idxen
s_waitcnt    vmcnt(0)
v_add_f32    v1, v0, v1
v_mul_f32    v0, v2, v1
v_mul_f32    v1, v3, v1
buffer_store_format_xyzw  v[0:3], v4, s[0:3], 0 idxen glc
```

# GLOBAL VALUE NUMBERING (GVN)

- Track value equivalence across basic blocks

```
[numthreads(8,4,1)]
void CSMain(uint3 did : SV_DispatchThreadId)
{
    float4 color;
    if (did.x == did.y) {
        color = input[did.x + did.y];
    } else {
        color = input[2 * did.x];
    }
    output[4 * did.x + did.y] = color;
}
```

# GLOBAL VALUE NUMBERING (GVN)

- Track value equivalence across basic blocks

```
[numthreads(8,4,1)]
void CSMain(uint3 did : SV_DispatchThreadId)
{
    float4 color;
    if (did.x == did.y) {
        color = input[did.x + did.x];
    } else {
        color = input[2 * did.x];
    }
    output[4 * did.x + did.y] = color;
}
```



Equal to  $2 \times \text{did.x}$

# GLOBAL VALUE NUMBERING (GVN)

- Track value equivalence across basic blocks

```
[numthreads(8,4,1)]
void CSMain(uint3 did : SV_DispatchThreadId)
{
    float4 color;
    color = input[did.x + did.x];
    if (did.x == did.y) {
    } else {
    }
    output[4 * did.x + did.y] = color;
}
```

# GLOBAL VALUE NUMBERING (GVN)

- Track value equivalence across basic blocks

```
[numthreads(8,4,1)]
void CSMain(uint3 did : SV_DispatchThreadId)
{
    float4 color;
    color = input[did.x + did.x];
    output[4 * did.x + did.y] = color;
}
```

# GLOBAL VALUE NUMBERING (GVN)

- Track value equivalence across basic blocks

```
[numthreads(8,4,1)]
void CSMain(uint3 did : SV_DispatchThreadId)
{
    float4 color;
    color = input[did.x << 1];
    output[(did.x << 2) + did.y] = color;
}
```

# GLOBAL VALUE NUMBERING (GVN)

- Track value equivalence across basic blocks

```
v_lshlrev_b32  v2, 1, v0
buffer_load_format_xyzw  v[2:5], v2, s[4:7], 0 idxen
v_lshl_add_u32  v1, v0, 2, v1
s_waitcnt      vmcnt(0)
buffer_store_format_xyzw  v[2:5], v1, s[8:11], 0 idxen
```

# STRENGTH REDUCTION

- Replace expensive operations by cheaper ones

```
[numthreads(8,4,1)]
void CSMain(uint3 did : SV_DispatchThreadId)
{
    output[did.xy] = input[did.xy] / scale;
}
```

# STRENGTH REDUCTION

- Replace expensive operations by cheaper ones

```
image_load    v[3:6], [v2,v1], s[20:27] dmask:0xf dim:SQ_RSRC_IMG_2D unorm
s_buffer_load_dword s0, s[12:15], null
s_waitcnt     lgkmcnt(0)
v_rcp_f32    v0, s0
s_waitcnt     vmcnt(0)
v_mul_f32    v3, v3, v0
v_mul_f32    v4, v4, v0
v_mul_f32    v5, v5, v0
v_mul_f32    v6, v6, v0
image_store   v[3:6], [v2,v1], s[4:11] dmask:0xf dim:SQ_RSRC_IMG_2D unorm
```



Reciprocal instead of division



Shared by all components (CSE)

# STRENGTH REDUCTION

- Replace expensive operations by cheaper ones

```
[numthreads(8,4,1)]
void CSMain(uint3 did : SV_DispatchThreadId)
{
    output[did.xy] = input[did.xy / 3];
}
```



Integer division by constant

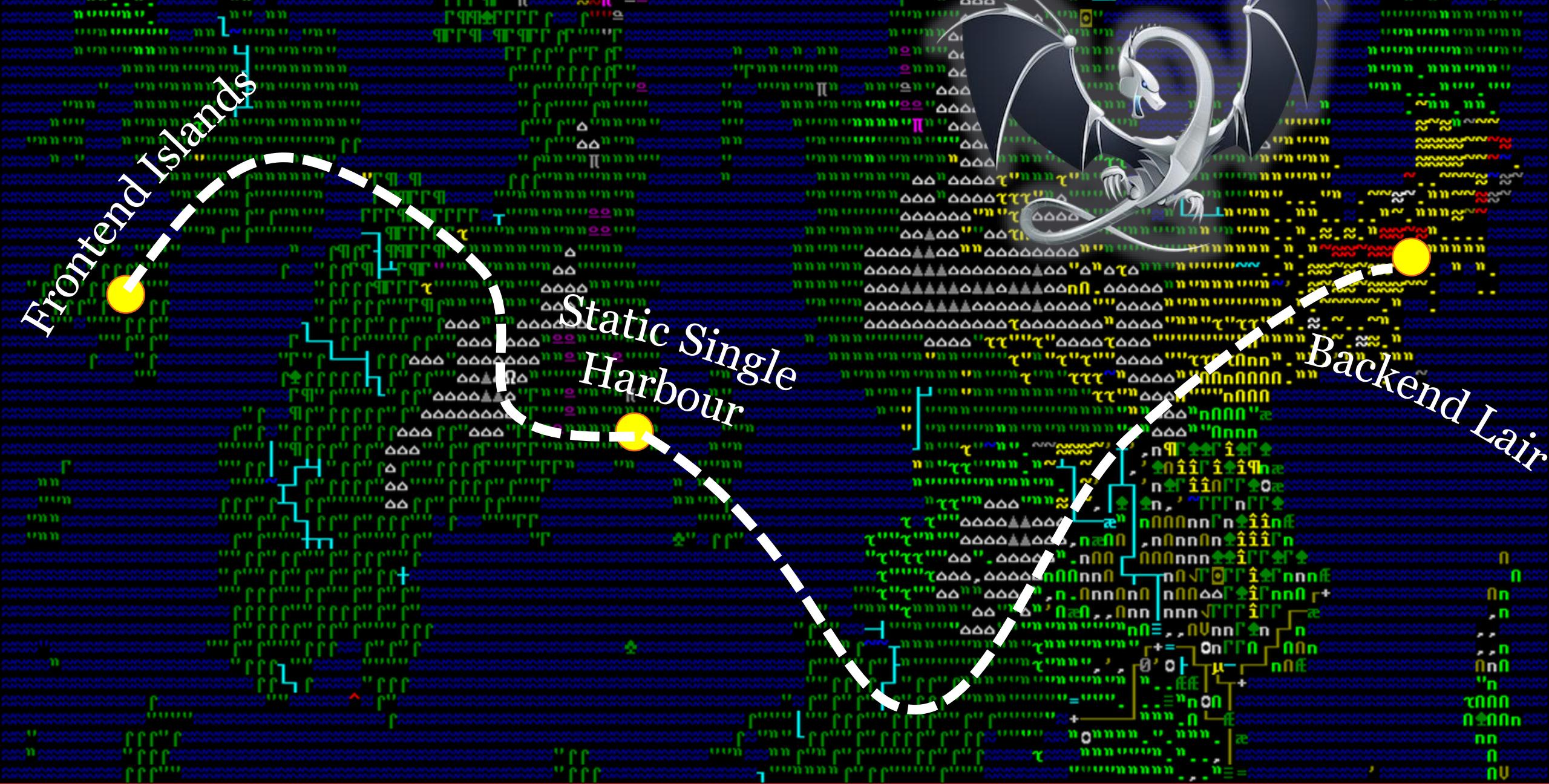
# STRENGTH REDUCTION

- Replace expensive operations by cheaper ones

```
v_mul_hi_u32 v0, v2, lit(0aaaaaaaaab)
v_mul_hi_u32 v3, v1, lit(0aaaaaaaaab)
v_lshrev_b32 v0, 1, v0
v_lshrev_b32 v3, 1, v3
s_waitcnt    lgkmcnt(0)
image_load   v[3:6], [v0,v3], s[16:23] dmask:0xf dim:SQ_RSRC_IMG_2D unorm
s_waitcnt    vmcnt(0)
image_store   v[3:6], [v2,v1], s[4:11] dmask:0xf dim:SQ_RSRC_IMG_2D unorm
s_endpgm
```



Multiply-and-shift



# THE BACKEND

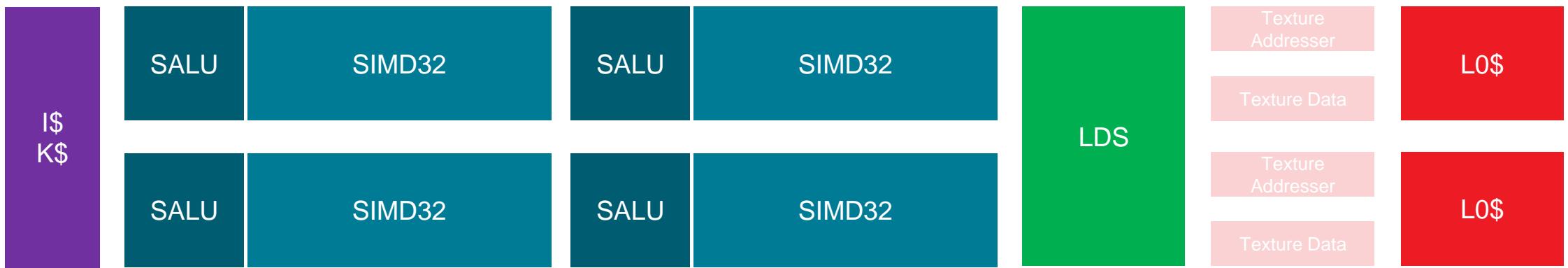
- Here, the IR meets the HW
- The backend is designed to
  - Perform HW-specific optimizations
  - Translate high-level constructs into HW instructions
  - Optimize

# MEMORY ACCESS

- The backend compiler knows which caches are used for every instruction
- Everything before the backend compiler assumes a unified, coherent cache
- I.e. write-followed-by-read just works

# MEMORY ACCESS

- On RDNA, we have various separate caches
- K\$ is read-only, shared among all SIMD32; L0\$ is read-write, also shared, but not **coherent** with K\$



# MEMORY ACCESS



# MEMORY ACCESS

```
RWStructuredBuffer<int> inputBuffer0 : register(u0);
cbuffer inputBuffer1 : register(b0)
{
    int constants[64];
};
RWBuffer<float4> outputBuffer : register(u1);

[numthreads(64,1,1)]
void CSMain(uint3 did : SV_DispatchThreadId)
{
    outputBuffer[did.x] = inputBuffer0[did.y] + constants[did.y];
}
```

# MEMORY ACCESS

- `inputBuffer0` could alias with `outputBuffer`: Must go through L0\$
- `inputBuffer1` does not alias with `outputBuffer`: Can go through K\$

```
buffer_load_dword  v1, v1, s[4:7], 0 idxen          // 000000000014: E0302000 80010101
s_buffer_load_dword  s0, s[12:15], s1            // 00000000001C: F4200006 02000000
```

# MEMORY ACCESS

- HW can also convert formats along the way
- This depends on what type of load it is!



# BUFFER TYPES MATTER

```
Buffer<float4> inputBuffer;  
RWBuffer<float> outputBuffer;
```

```
[numthreads(8,4,1)]  
void CSMain(uint3 did : SV_DispatchThreadId)  
{  
    outputBuffer[did.x] = inputBuffer[did.x][did.y];  
}
```

```
...  
buffer_load_format_xyzw v[0:3],  
    v4, s[8:11], 0 idxen  
s_waitcnt    vmcnt(0)  
v_cndmask_b32 v2, v3, v2, vcc  
v_cndmask_b32 v1, v2, v1, s[6:7]  
v_cndmask_b32 v0, v1, v0, s[4:5]  
...
```

```
StructuredBuffer<float4> inputBuffer;  
RWBuffer<float> outputBuffer;  
  
[numthreads(8,4,1)]  
void CSMain(uint3 did : SV_DispatchThreadId)  
{  
    outputBuffer[did.x] = inputBuffer[did.x][did.y];  
}
```

```
...  
s_waitcnt    lgkmcnt(0)  
buffer_load_dword  v0, v0, s[8:11], 0 offen  
s_load_dwordx4 s[0:3], s[0:1], null  
s_waitcnt    vmcnt(0)  
v_mov_b32    v1, v0  
v_mov_b32    v2, v0  
v_mov_b32    v3, v0  
...
```

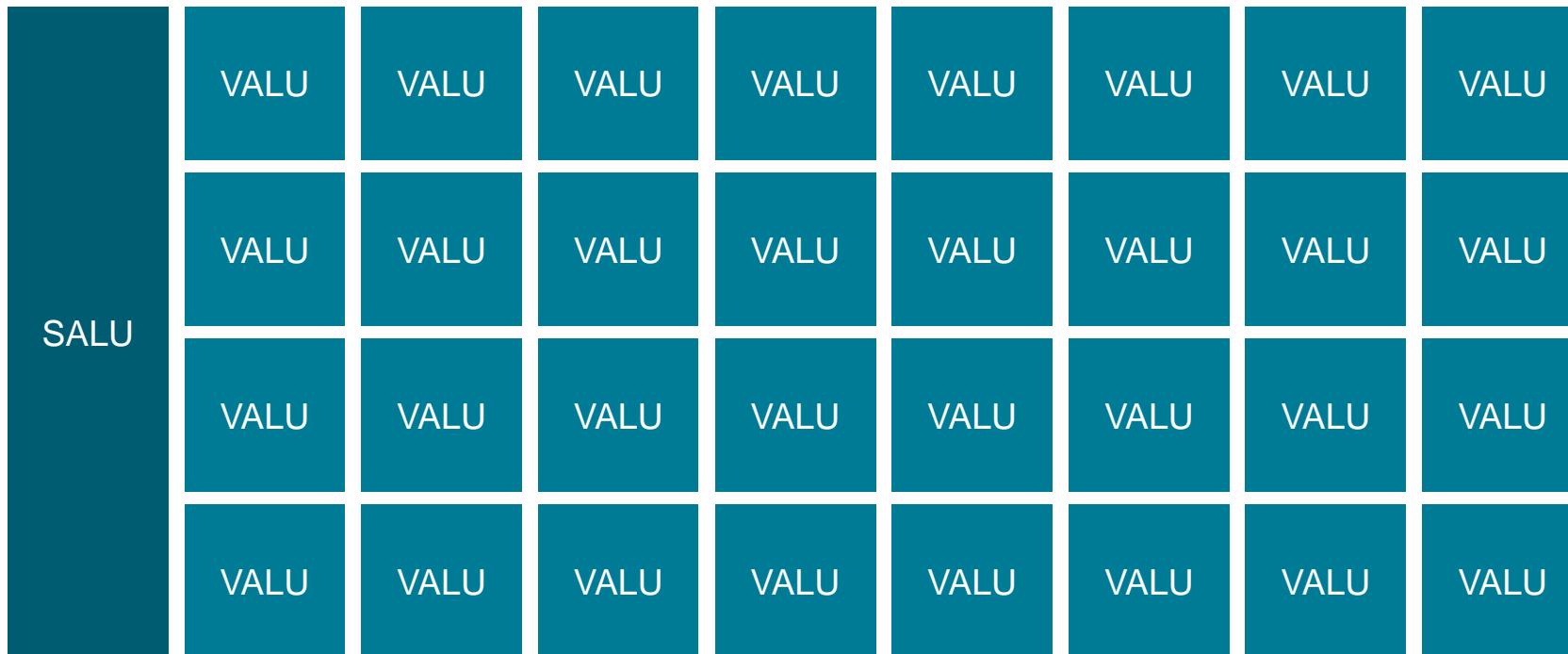
# EXECUTION MODEL

- A GPU doesn't execute code like a CPU



# EXECUTION MODEL

- Scalar ALU core with it's on scalar register file
- Vector ALU attached to it with a separate vector register file (with one register per lane)
- VALU is turned on/off using an execution mask



# EXECUTION MODEL

- Scalar branch – branch over scalar value

```
cbuffer inputBuffer0 : register(b0) {
    int constants[64];
};

RWByteAddressBuffer outputBuffer : register(u0);

[numthreads(64,1,1)]
void CSMain(uint3 did : SV_DispatchThreadId)
{
    if (constants [0]) {
        outputBuffer.Store(did.x, 3);
    } else {
        outputBuffer.Store (did.x, 42);
    }
}
```



Uniform across the wave

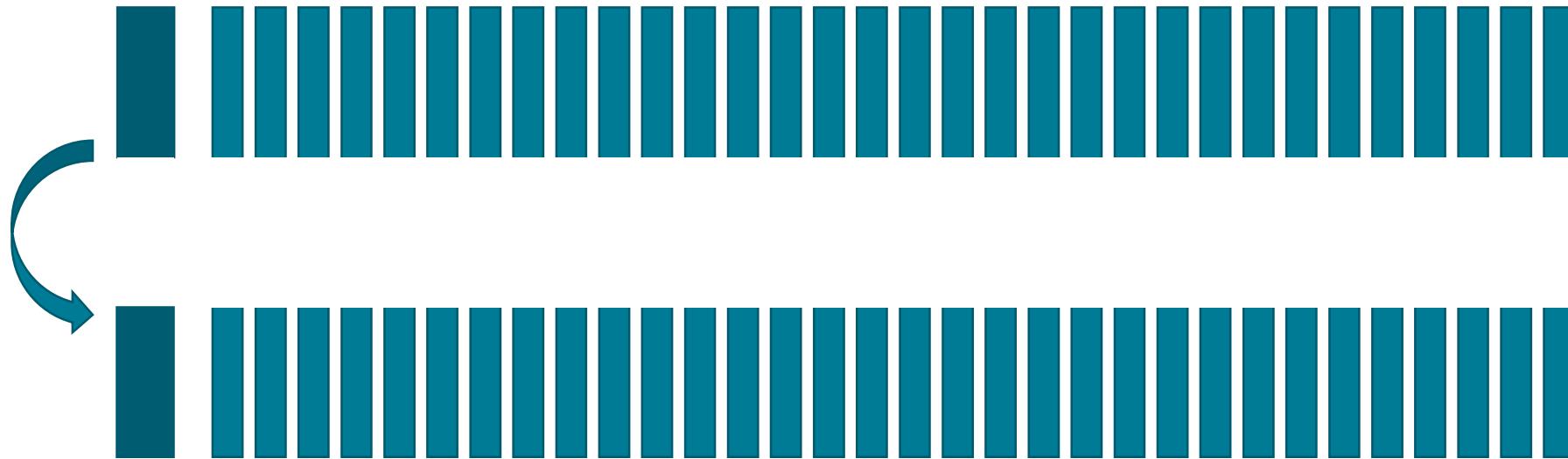
# EXECUTION MODEL

- Branches can only happen on SALU
- Scalar comparison, scalar branch

```
s_buffer_load_dword    s0, s[8:11], null
s_waitcnt      lgkmcnt(0)
s_cmp_eq_u32    s0, 0
s_cbranch_scc1   label_0030
v_mov_b32       v1, 3
buffer_store_dword  v1, v0, s[4:7], 0 offen
s_endpgm
label_0030:
v_mov_b32       v1, 42
buffer_store_dword  v1, v0, s[4:7], 0 offen
s_endpgm
```

# EXECUTION MODEL

- Scalar branching, execution mask is fully on/off



# EXECUTION MODEL

- Non-uniform branch

```
Buffer<int> inputBuffer0 : register(t0);  
RWByteAddressBuffer outputBuffer : register(u0);
```

```
[numthreads(64,1,1)]  
void CSMain(uint3 did : SV_DispatchThreadId)  
{  
    if (inputBuffer0[did.x]) {  
        outputBuffer.Store(did.x, 3);  
    } else {  
        outputBuffer.Store(did.x, 42);  
    }  
}
```

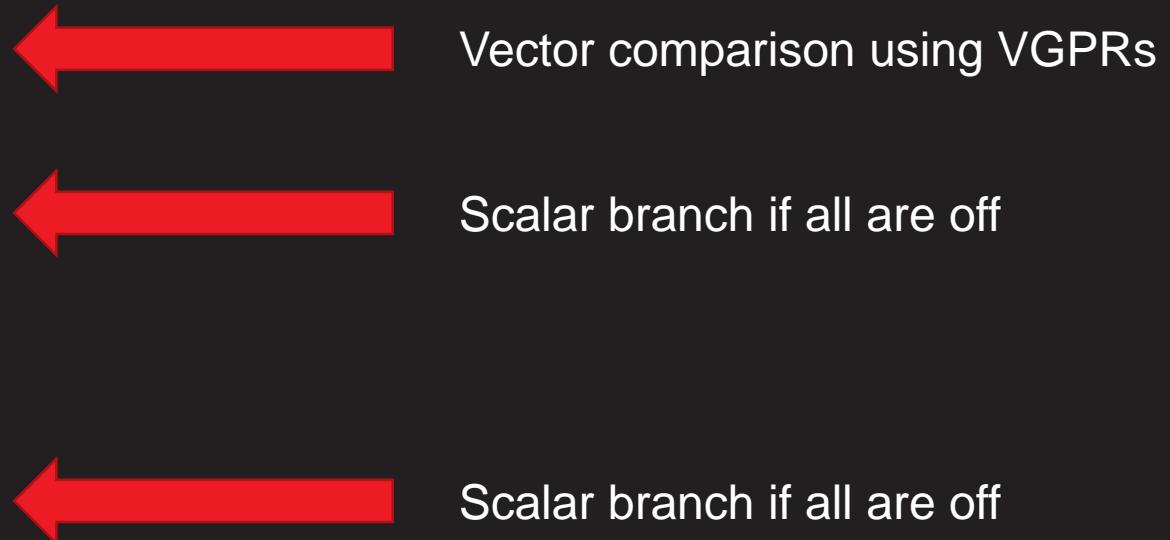


Varying across the wave

# EXECUTION MODEL

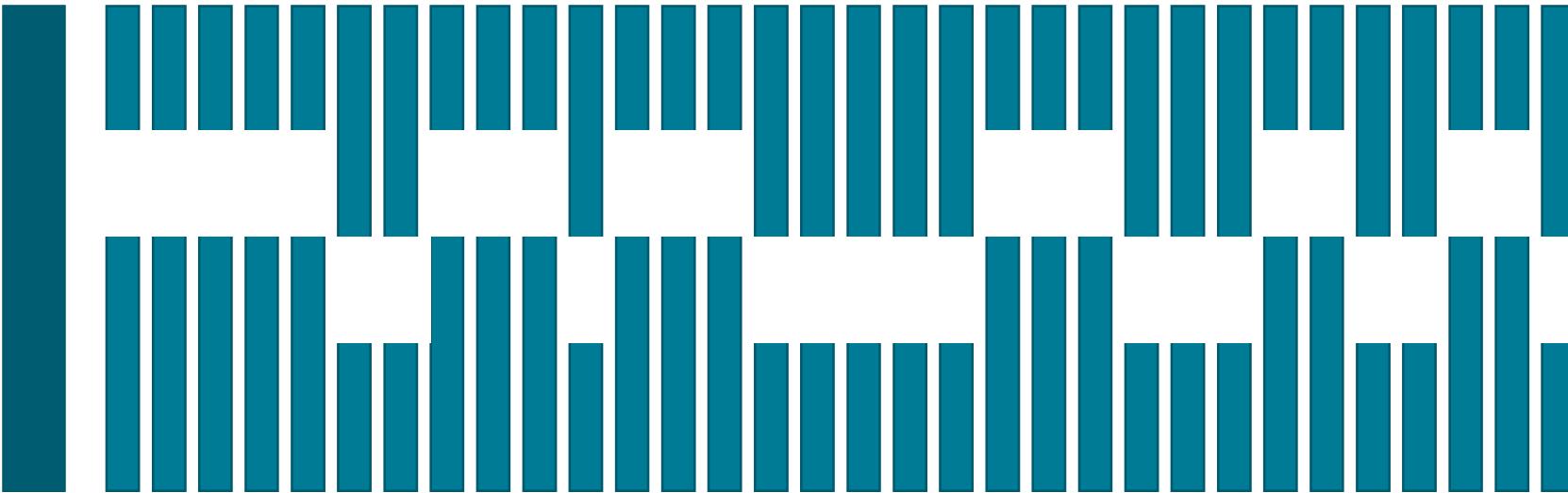
- Non-uniform data – branch is no longer uniform unless it happens that all lanes produce the same result

```
buffer_load_format_x  v1, v0, s[4:7], 0 idxen
s_waitcnt      vmcnt(0)
v_cmp_ne_u32  vcc_lo, 0, v1
  s_and_saveexec_b32  s0, vcc_lo
  v_mov_b32    v1, 3
s_cbranch_execz  label_0030
  buffer_store_dword  v1, v0, s[8:11], 0 offen
label_0030:
  s_andn2_b32  exec_lo, s0, exec_lo
  v_mov_b32    v1, 42
s_cbranch_execz  label_0044
  buffer_store_dword  v1, v0, s[8:11], 0 offen
label_0044:
  s_endpgm
```



# EXECUTION MODEL

- Non-uniform control flow == execution mask if not all zero or one



# EXECUTION MODEL

- Could also remove the optimization to prefer a scalar jump without loss of functionality

```
buffer_load_format_x  v1, v0, s[4:7], 0 idxen
s_waitcnt      vmcnt(0)
v_cmp_ne_u32  vcc_lo, 0, v1
  s_and_saveexec_b32  s0, vcc_lo
  v_mov_b32    v1, 3
  buffer_store_dword  v1, v0, s[8:11], 0 offen
label_0030:
  s_andn2_b32  exec_lo, s0, exec_lo
  v_mov_b32    v1, 42
  buffer_store_dword  v1, v0, s[8:11], 0 offen
s_endpgm
```



Vector comparison using VGPRs

# GENERAL RULES

- Combining varying & uniform values ...

Input 1	Input 2	Output
Varying	Varying	Varying
Uniform	Varying	Varying
Varying	Uniform	Varying
Uniform	Uniform	Uniform

- This includes loads (i.e. load using varying index – varying load!)
- All of this is automatic

# UNIFORMITY AND BUFFERS

- Loading a constant using a uniform index (did.y same for all threads in a wave)

```
cbuffer Constants {
    float constants[256];
}
RWStructuredBuffer<float> output;

[numthreads(64,1,1)]
void CSMain(uint3 did : SV_DispatchThreadId)
{
    output[did.x] = constants[did.y];
}
```

# UNIFORMITY AND BUFFERS

- Yields scalar load as expected

```
s_and_b32      s0, s13, lit(0x00fffff)
s_lshl_b32    s0, s0, 4
s_buffer_load_dword  s0, s[8:11], s0
v_mad_u32_u24  v0, s12, 64, v0
s_waitcnt      lgkmcnt(0)
v_mov_b32      v1, s0
buffer_store_dword v1, v0, s[4:7], 0 idxen
```

# UNIFORMITY AND BUFFERS

- Loading a constant using a varying index

```
cbuffer Constants {
    float constants[256];
}
RWStructuredBuffer<float> output;

[numthreads(64,1,1)]
void CSMain(uint3 did : SV_DispatchThreadId)
{
    output[did.x] = constants[did.x];
}
```

# UNIFORMITY AND BUFFERS

- Yields a non-scalar load

```
v_mad_u32_u24  v0, s12, 64, v0
tbuffer_load_format_x  v1, v0, s[8:11], 0 idxen ...
s_waitcnt      vmcnt(0)
buffer_store_dword  v1, v0, s[4:7], 0 idxen
```

# UNIFORMITY AND CONTROL FLOW

- Propagating divergence gets tricky with control flow

```
StructuredBuffer<uint> wordCode;
RWStructuredBuffer<uint> output;

[numthreads(64,1,1)]
void CSMain(uint3 did : SV_DispatchThreadId)
{
    uint x = did.x;
    for (uint pc = 0;;) {
        uint instruction = wordCode[pc++];
        if (instruction == 0 && x == 0) break;
        ...
    }
    output[did.x] = pc;
}
```



pc is uniform

break is divergent

# UNIFORMITY AND CONTROL FLOW

```
v_mov_b32 v1, v0
s_mov_b32 s9, 0
s_mov_b32 s10, 0
s_mov_b32 s4, exec_lo
label_header:
    s_buffer_load_dword s8, s[4:7], s10
    s_add_i32 s9, s9, 1
    s_add_i32 s10, s10, 4
    s_waitcnt lgkmcnt(0)
    v_or_b32_e32 v2, s8, v1
    v_cmp_eq_u32_e32 vcc_lo, 0, v2
    v_mov_b32_e32 v2, s9
    s_andn2_b32 exec_lo, exec_lo, vcc_lo
    s_cbranch_execz label_exit
    ...
label_exit:
    s_mov_b32 exec_lo, s3
    v_lshlrev_b32_e32 v0, 2, v0
    buffer_store_dword v2, v0, s[0:3], 0 offen
```

Setup pc

Fetch instruction & update pc

Save into a vector register

Store the divergent value

# CROSSING THE BRIDGE

- Going from scalar to vector is a simple broadcast
- Going from vector to scalar register is not so simple
  - What-if values are not uniform in the register file?
  - Commonly known as “scalarization”
- AKA “ReadFirstLane”, “ReadLane”

# AUTOMATIC SCALARIZATION

- Sometimes, the compiler can do it automatically
- In the following example, `inputBuffer0[did.x]` is non-uniform, but `outputBuffer[0]` clearly is uniform
- Goal: Compute sum across VGPRs, then execute a single atomic on one lane

```
Buffer<int> inputBuffer0;
RWBuffer<int> outputBuffer;

[numthreads(64,1,1)]
void CSMain(uint3 did : SV_DispatchThreadId)
{
    InterlockedAdd(outputBuffer[0], inputBuffer0[did.x]);
}
```

# AUTOMATIC SCALARIZATION

```
v_add_nc_u32    v2, v2, v2 row_shr:1
v_add_nc_u32    v2, v2, v2 row_shr:2
v_add_nc_u32    v2, v2, v2 row_shr:4
v_add_nc_u32    v2, v2, v2 row_shr:8
s_mov_b32       exec_lo, lit(0xfffff0000)
s_movk_i32      s1, 0xffff
v_permlanex16_b32 v3, v2, -1, s1 fi:1
v_add_nc_u32    v2, v3, v2
s_mov_b32       exec_lo, s0
v_readlane_b32  s0, v2, 31
v_mov_b32       v0, 0
v_mov_b32       v1, s0
s_ff1_i32_b64   s0, exec
s_lshl_b64      s[0:1], 1, s0
s_and_saveexec_b64 s[0:1], s[0:1]
buffer_atomic_add v1, v0, s[8:11], 0 idxen
```

Reduce using cross-lane operations

Load result into SGPR

Turn off all lanes but one

# SCALARIZATION

- If we know the VALU only has a few separate values, we could process them all in turn using the SALU
- “Waterfall loop”
- Use case on RDNA: Texture descriptors live in scalar registers. What if we want to load different textures per lane?

```
float4 result = textureArray1[  
    NonUniformResourceIndex(index)].SampleGrad(textureSampler, uv, grad.xy, grad.zw);
```

# AUTOMATIC SCALARIZATION

```
label_00C0:  
    s_waitcnt    vmcnt(0)  
    v_readfirstlane_b32  s6, v6  ← Promote current index to scalar; turn on all lanes which  
    v_cmp_eq_u32   vcc, s6, v6   use the same value  
    s_and_saveexec_b32  s7, vcc_lo  
    s_cbranch_execz  label_00FC  
    s_load_dwordx8  s[12:19], s[0:11] ← Load descriptor  
    s_waitcnt    lgkmcnt(0)  
    s_waitcnt_depctr  0xffe3  
    image_sample_d  v[6:9], [v2,v3,v4,v5,v0,v1], s[12:19], s[24:27] dmask:0xf dim:SQ_RSRC_IMG_2D  
    s_andn2_b32   s4, s4, exec_lo ← Check if done, if so, terminate  
    s_cbranch_scc0  label_010C  
  
label_00FC:  
    v_nop  
    s_mov_b32    exec_lo, s7  
    s_and_b32    exec_lo, exec_lo ← Disable lanes and loop again  
    s_branch    label_00C0  
  
label_010C:
```

# MANUAL SCALARIZATION

- Manual scalarization – if you know the data will be uniform for all threads in a wave, you can convert a VGPR to a SGPR yourself

```
[numthreads(64,1,1)]
void CSMain(uint3 did : SV_DispatchThreadId)
{
    if (WaveReadLaneFirst(inputBuffer0[did.x])) {
        outputBuffer.Store(did.x, 3);
    } else {
        outputBuffer.Store(did.x, 42);
    }
}
```

# MANUAL SCALARIZATION

```
v_readlane_b32    s0, v1, s0          ← Promote value from first active lane to SGPR
s_mov_b32         s2, s5
s_mov_b32         s3, s1
s_load_dwordx4   s[4:7], s[2:3], null
s_cmp_eq_i32     s0, 0
s_cbranch_scc1   label_0070          ← Fully scalar branch as a result
v_mov_b32         v1, 3
s_waitcnt         lgkmcnt(0)
buffer_store_dword v1, v0, s[4:7], 0 offen glc
s_endpgm
label_0070:
v_mov_b32         v1, 42
s_waitcnt         lgkmcnt(0)
s_waitcnt_depctr 0xffe3
buffer_store_dword v1, v0, s[4:7], 0 offen glc
s_endpgm
```

# TAKEAWAY

- It's a long way from high level language to ISA
- Translation to IR is generally lossy
- SSA form makes certain optimizations trivial, especially around constants and dead-code
- The backend has to extract uniform/varying information from a high level language and IR which doesn't care

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**THAT'S ALL FOLKS!**

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